

# Lecture 8

## Global Cauchy theorem

MATH 503, FALL 2025

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# Chains and cycles

- Suppose  $\gamma_1, \dots, \gamma_n$  are paths in  $\mathbb{C}$ , and set  $K = \gamma_1^* \cup \dots \cup \gamma_n^*$ . Let  $C(K)$  be the vector space of continuous functions on  $K$ . Each  $\gamma_i$  induces a linear functional  $\tilde{\gamma}_i$  on  $C(K)$ , by the formula

$$\tilde{\gamma}_i(f) = \int_{\gamma_i} f(z) dz.$$

- Define  $\tilde{\Gamma} = \tilde{\gamma}_1 + \dots + \tilde{\gamma}_n$  or more explicitly,

$$\tilde{\Gamma}(f) = \tilde{\gamma}_1(f) + \dots + \tilde{\gamma}_n(f), \quad \text{for } f \in C(K). \quad (*)$$

- The relation (\*) suggests that we introduce a “formal sum”

$$\Gamma = \gamma_1 \dot{+} \dots \dot{+} \gamma_n,$$

and define

$$\int_{\Gamma} f(z) dz = \tilde{\Gamma}(f) = \sum_{i=1}^n \int_{\gamma_i} f(z) dz, \quad \text{for } f \in C(K).$$

# Chains and cycles

Let  $\gamma_1, \dots, \gamma_n$  be paths such that  $\gamma_i^* \subset \Omega$  for  $1 \leq i \leq n$ .

- Let  $\Gamma$  be a formal sum as before given by

$$\Gamma = \gamma_1 \dot{+} \cdots \dot{+} \gamma_n. \quad (**)$$

Then we say that  $\Gamma$  is a **chain** in  $\Omega$ .

- If there exists a representation of a chain  $\Gamma$  such that each  $\gamma_i$  is a closed path in  $\Omega$ , then we say that  $\Gamma$  is a **cycle** in  $\Omega$ .
- By a combinatorial argument, it can be shown that a chain  $\Gamma$  is a cycle if and only if in any representation of  $\Gamma$ , the initial and end points of  $\gamma_i$  are identical in pairs.
- If  $(**)$  holds, then we define  $\Gamma^* = \gamma_1^* \cup \cdots \cup \gamma_n^*$ .
- The relation  $(**)$  means that we are adding paths in the context of adding linear functionals  $(*)$ ; otherwise, it would not be meaningful.

# Chains and cycles

- If  $\Gamma$  is a cycle and  $\alpha \notin \Gamma^*$ , we define the index of  $\alpha$  with respect to  $\Gamma$  by

$$\text{Ind}_{\Gamma}(\alpha) = \frac{1}{2\pi i} \int_{\Gamma} \frac{dz}{z - \alpha}.$$

- Obviously,  $(**)$  implies

$$\text{Ind}_{\Gamma}(\alpha) = \sum_{i=1}^n \text{Ind}_{\gamma_i}(\alpha).$$

- If each  $\gamma_i$  in  $(**)$  is replaced by its opposite path  $-\gamma_i$ , the resulting chain will be denoted by  $-\Gamma$ . Then

$$\int_{-\Gamma} f(z) dz = - \int_{\Gamma} f(z) dz \quad \text{for } f \in C(\Gamma^*).$$

- In particular,  $\text{Ind}_{-\Gamma}(\alpha) = -\text{Ind}_{\Gamma}(\alpha)$  if  $\Gamma$  is a cycle and  $\alpha \notin \Gamma^*$ .

# Chains and cycles

- Chains can be added and subtracted in the obvious way, by adding or subtracting the corresponding functionals.
- The statement  $\Gamma = k_1\Gamma_1 + k_2\Gamma_2$  for any integers  $k_1, k_2 \in \mathbb{Z}$  means that

$$\int_{\Gamma} f(z)dz = k_1 \int_{\Gamma_1} f(z)dz + k_2 \int_{\Gamma_2} f(z)dz \quad \text{for all } f \in C(\Gamma_1^* \cup \Gamma_2^*).$$

- Finally, note that a chain may be represented as a sum of paths in many ways. To say that

$$\gamma_1 + \cdots + \gamma_n = \delta_1 + \cdots + \delta_k$$

means simply that

$$\sum_{i=1}^n \int_{\gamma_i} f(z)dz = \sum_{j=1}^k \int_{\delta_j} f(z)dz$$

for every  $f$  that is continuous on  $\gamma_1^* \cup \cdots \cup \gamma_n^* \cup \delta_1^* \cup \cdots \cup \delta_k^*$ .

- In particular, a cycle may very well be represented as a sum of paths that are not closed.

# Global Cauchy's theorem

## Theorem

Suppose  $f \in H(\Omega)$ , where  $\Omega$  is an arbitrary open set in the complex plane.

- If  $\Gamma$  is a cycle in  $\Omega$  that satisfies  $\text{Ind}_{\Gamma}(\alpha) = 0$  for every  $\alpha \notin \Omega$ , then

$$f(z) \cdot \text{Ind}_{\Gamma}(z) = \frac{1}{2\pi i} \int_{\Gamma} \frac{f(w)}{w - z} dw \quad \text{for } z \in \Omega \setminus \Gamma^*, \quad (\text{A})$$

and

$$\int_{\Gamma} f(z) dz = 0, \quad (\text{B})$$

- If  $\Gamma_0$  and  $\Gamma_1$  are cycles in  $\Omega$  such that  $\text{Ind}_{\Gamma_0}(\alpha) = \text{Ind}_{\Gamma_1}(\alpha)$  for every  $\alpha \notin \Omega$ , then

$$\int_{\Gamma_0} f(z) dz = \int_{\Gamma_1} f(z) dz. \quad (\text{C})$$

# Global Cauchy's theorem

**Proof:** The function  $g$  defined in  $\Omega \times \Omega$  by

$$g(z, w) = \begin{cases} \frac{f(w) - f(z)}{w - z} & \text{if } w \neq z, \\ f'(z) & \text{if } w = z, \end{cases}$$

is continuous in  $\Omega \times \Omega$  (see the previous lecture).

- Hence we can define

$$h(z) = \frac{1}{2\pi i} \int_{\Gamma} g(z, w) dw \quad \text{for } z \in \Omega.$$

- For  $z \in \Omega \setminus \Gamma^*$ , the Cauchy formula (A) is clearly equivalent to the assertion that

$$h(z) = 0.$$

- To prove that  $h(z) = 0$ , let us first prove that  $h \in H(\Omega)$ .

# Global Cauchy's theorem

- We first show that  $h$  is continuous in  $\Omega$ .
- Observe that  $g$  is uniformly continuous on every compact subset of  $\Omega \times \Omega$ . If  $z \in \Omega$  and  $(z_n)_{n \in \mathbb{N}} \subseteq \Omega$ , and  $\lim_{n \rightarrow \infty} z_n = z$ , it follows that  $\overline{\{z_n : n \in \mathbb{N}\}} \times \Gamma^*$  is a compact subset of  $\Omega \times \Omega$ , and consequently  $\lim_{n \rightarrow \infty} g(z_n, w) = g(z, w)$  uniformly for  $w \in \Gamma^*$ .
- Hence  $\lim_{n \rightarrow \infty} h(z_n) = h(z)$ , proving that  $h$  is continuous in  $\Omega$ .
- Let  $\Delta$  be a closed triangle in  $\Omega$ . Then by Fubini's theorem

$$\int_{\partial\Delta} h(z) dz = \frac{1}{2\pi i} \int_{\Gamma} \left( \int_{\partial\Delta} g(z, w) dz \right) dw.$$

- For each  $w \in \Omega$  the function  $z \mapsto g(z, w)$  is holomorphic in  $\Omega$ , since the singularity at  $z = w$  is removable.
- The inner integral over  $\partial\Delta$  is therefore 0 for every  $w \in \Gamma^*$ . Thus Morera's theorem shows now that  $h \in H(\Omega)$  as desired.



# Global Cauchy's theorem

- Let  $\Omega_1 = \{z \in \mathbb{C} : \text{Ind}_\Gamma(z) = 0\}$ . Then  $\Omega^c \subseteq \Omega_1$ , since  $\text{Ind}_\Gamma(\alpha) = 0$  for all  $\alpha \in \Omega^c$ . Moreover,  $\Omega_1$  is open since the index function  $\text{Ind}_\Gamma : \mathbb{C} \setminus \Gamma^* \rightarrow \mathbb{Z}$  is continuous. Also  $\Omega_1$  contains the unbounded component of the complement of  $\Gamma^*$ , since  $\text{Ind}_\Gamma(z)$  is 0 there.

- Define

$$h_1(z) = \frac{1}{2\pi i} \int_\Gamma \frac{f(w)}{w - z} dw \quad \text{for } z \in \Omega_1.$$

- If  $z \in \Omega \cap \Omega_1$ , the definition of  $\Omega_1$  makes it clear that  $h_1(z) = h(z)$ .
- Hence there is a function  $\varphi \in H(\Omega \cup \Omega_1)$  whose restriction to  $\Omega$  is  $h$  and whose restriction to  $\Omega_1$  is  $h_1$ .
- Since  $\Omega \cup \Omega_1 = \mathbb{C}$ , thus  $\varphi$  is an entire function. Hence

$$\lim_{|z| \rightarrow \infty} \varphi(z) = \lim_{|z| \rightarrow \infty} h_1(z) = 0.$$

- Liouville's theorem implies now that  $\varphi(z) = 0$  for every  $z \in \mathbb{C}$ . This proves that  $h(z) = 0$ , and hence (A).

# Global Cauchy's theorem

- To deduce (B) from (A), pick  $a \in \Omega \setminus \Gamma^*$  and define

$$F(z) = (z - a)f(z).$$

Since  $F(a) = 0$ , and using (A) we obtain

$$\frac{1}{2\pi i} \int_{\Gamma} f(z) dz = \frac{1}{2\pi i} \int_{\Gamma} \frac{F(z)}{z - a} dz = F(a) \cdot \text{Ind}_{\Gamma}(a) = 0.$$

- To prove (C) let  $\Gamma = \Gamma_1 - \Gamma_0$ . By our assumptions  $\text{Ind}_{\Gamma}(\alpha) = 0$  for every  $\alpha \in \Omega^c$ , hence by (B) we obtain

$$\int_{\Gamma} f(z) dz = 0.$$

- This is equivalent to statement (C):

$$\int_{\Gamma_0} f(z) dz = \int_{\Gamma_1} f(z) dz.$$

since  $\Gamma = \Gamma_1 - \Gamma_0$ . This completes the proof. □

# Global Cauchy's theorem

## Corollary

Let  $\Omega \subseteq \mathbb{C}$  be an open set and  $f \in H(\Omega)$ , and let  $\Gamma$  be a cycle in  $\Omega$ . Then the following statements are equivalent:

(i)

$$f(z) \cdot \text{Ind}_{\Gamma}(z) = \frac{1}{2\pi i} \int_{\Gamma} \frac{f(w)}{w - z} dw \quad \text{for } z \in \Omega \setminus \Gamma^*.$$

(ii)

$$\int_{\Gamma} f(z) dz = 0.$$

(iii)

$$\text{Ind}_{\Gamma}(\alpha) = 0 \quad \text{for every } \alpha \in \mathbb{C} \setminus \Omega.$$

# Global Cauchy's theorem

**Proof (i)  $\implies$  (ii):** Pick  $a \in \Omega \setminus \Gamma^*$  and define

$$F(z) = (z - a)f(z).$$

Since  $F(a) = 0$ , and using (i) we obtain

$$\frac{1}{2\pi i} \int_{\Gamma} f(z) dz = \frac{1}{2\pi i} \int_{\Gamma} \frac{F(z)}{z - a} dz = F(a) \cdot \text{Ind}_{\Gamma}(a) = 0. \quad \square$$

**Proof (ii)  $\implies$  (iii):** For  $a \in \mathbb{C} \setminus \Omega$  the function  $f(z) = (z - a)^{-1}$  is holomorphic in  $\Omega$ . By (ii), since  $\Gamma \subseteq \Omega$ , we obtain

$$\text{Ind}_{\Gamma}(a) = \frac{1}{2\pi i} \int_{\Gamma} \frac{1}{z - a} dz = 0.$$

**Proof (iii)  $\implies$  (i):** This implication follows from the global Cauchy theorem. This completes the proof of the corollary.  $\square$

# Global Cauchy's theorem

## Remarks

- (a) If  $\gamma$  is a closed path in a convex region  $\Omega$  and if  $\alpha \notin \Omega$ , an application of the Cauchy theorem for convex sets to  $f(z) = (z - \alpha)^{-1}$  shows that

$$\text{Ind}_{\gamma}(\alpha) = 0.$$

- Therefore the hypothesis of the global Cauchy theorem is therefore satisfied by every cycle in  $\Omega$  if  $\Omega$  is convex.
- This shows that the global Cauchy theorem generalizes Cauchy theorem and the Cauchy integral theorem for convex regions.

# Global Cauchy's theorem

## Remarks

- (b) In order to apply the global Cauchy theorem, it is desirable to have a reasonably efficient method of finding the index of a point with respect to a closed path. Here the concept of the winding number, which coincides with the index function for closed paths will help.
- Let  $\gamma : [a, b] \rightarrow \mathbb{C}$  be a closed path and  $z_0 \notin \gamma^*$ . Suppose that  $\theta_{z_0}$  is a continuous argument of  $\gamma - z_0$ . We recall that the **winding number** of  $z_0$  with respect to  $\gamma$ , is defined by

$$W(\gamma, z_0) = \frac{\theta_{z_0}(b) - \theta_{z_0}(a)}{2\pi}.$$

- It was shown last time that

$$W(\gamma, z_0) = \frac{1}{2\pi i} \int_{\gamma} \frac{1}{w - z_0} dw = \text{Ind}_{\gamma}(z_0).$$

# Global Cauchy's theorem

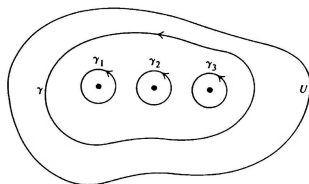
## Remarks

- The winding number  $W(\gamma, z_0)$  computes precisely the number of times  $\gamma$  loops around  $z_0$ . Since  $W(\gamma, z_0)$  is independent of the choice of continuous argument, we can analyze the change in argument of the quantity  $w - z_0$  as  $w$  travels along  $\gamma$ .
- Each time  $\gamma$  loops around  $z_0$  in an **anticlockwise direction**, then  $\frac{1}{2\pi} \arg(w - z_0)$  **increases** by 1. Conversely, if  $\gamma$  loops around  $z_0$  in a **clockwise direction**, then  $\frac{1}{2\pi} \arg(w - z_0)$  **decreases** by 1.
- (c) The last part of the global Cauchy theorem shows under what circumstances integration over one cycle can be replaced by integration over another, without changing the value of the integral.

# Global Cauchy's theorem, examples

## Example 1

- Let  $\gamma$  be a closed path, as below, in an open set  $U \subseteq \mathbb{C}$ , and let  $f$  be holomorphic on  $U$ .



- In that figure, we see that  $\gamma$  winds around the three points  $z_1, z_2, z_3$ , and winds once, hence  $\text{Ind}_\gamma(z_1) = \text{Ind}_\gamma(z_2) = \text{Ind}_\gamma(z_3) = 1$ .
- Let  $\gamma_1, \gamma_2, \gamma_3$  be small circles centered at  $z_1, z_2, z_3$  respectively, and oriented anticlockwise. Then we see that

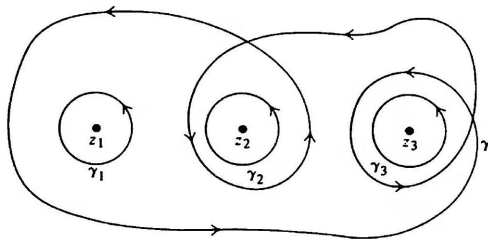
$$\int_{\gamma} f(z) dz = \int_{\gamma_1} f(z) dz + \int_{\gamma_2} f(z) dz + \int_{\gamma_3} f(z) dz.$$



# Global Cauchy's theorem, examples

## Example 2

- Let  $\gamma$  be the curve illustrated below, and let  $U$  be the plane from which three points  $z_1, z_2, z_3$  have been deleted. Let  $\gamma_1, \gamma_2, \gamma_3$  be small circles centered at  $z_1, z_2, z_3$  respectively, oriented counterclockwise.



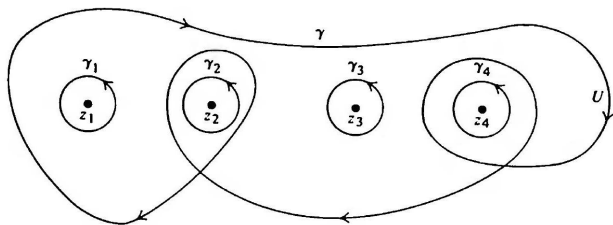
- Then  $\text{Ind}_\gamma(z_1) = 1$  and  $\text{Ind}_\gamma(z_2) = \text{Ind}_\gamma(z_3) = 2$  and consequently

$$\int_{\gamma} f(z) dz = \int_{\gamma_1} f(z) dz + 2 \int_{\gamma_2} f(z) dz + 2 \int_{\gamma_3} f(z) dz.$$

# Global Cauchy's theorem, examples

## Example 3

- Let  $\gamma$  be the curve illustrated below, and let  $U$  be the plane from which four points  $z_1, z_2, z_3, z_4$  have been deleted. Let  $\gamma_1, \gamma_2, \gamma_3, \gamma_4$  be small circles centered at  $z_1, z_2, z_3, z_4$  respectively, oriented clockwise.



- Then  $\text{Ind}_\gamma(z_1) = \text{Ind}_\gamma(z_3) = -1$  and  $\text{Ind}_\gamma(z_2) = \text{Ind}_\gamma(z_4) = -2$  and consequently

$$\int_{\gamma} f(z) dz = - \int_{\gamma_1} f(z) dz - 2 \int_{\gamma_2} f(z) dz - \int_{\gamma_3} f(z) dz - 2 \int_{\gamma_4} f(z) dz.$$

# Global Cauchy's theorem, example

In the proof of Laurent series representation we used the following form of the Cauchy integral formula:

## Theorem

*Let  $f$  be analytic on an open set  $\Omega$  containing the annulus  $\bar{A}(z_0, r_1, r_2)$  for  $0 < r_1 < r_2 < \infty$ , and let  $\gamma_1$  and  $\gamma_2$  denote the positively oriented inner and outer boundaries of the annulus. Then for  $z \in A(z_0, r_1, r_2)$ , we have*

$$f(z) = \frac{1}{2\pi i} \int_{\gamma_2} \frac{f(w)}{w - z} dw - \frac{1}{2\pi i} \int_{\gamma_1} \frac{f(w)}{w - z} dw$$

**Proof:** The proof is a consequence of the global Cauchy theorem applied to the cycle  $\Gamma = \gamma_2 - \gamma_1$ , since

$$\text{Ind}_{\Gamma}(\alpha) = 0 \quad \text{for} \quad \alpha \notin A(z_0, \rho_1, \rho_2),$$

where  $0 < \rho_1 < r_1 < r_2 < \rho_2 < \infty$  satisfy  $\bar{A}(z_0, \rho_1, \rho_2) \subset \Omega$ . □

# Homotopy

## Definition

Suppose  $\gamma_0$  and  $\gamma_1$  are closed curves in a topological space  $X$ , both with parameter interval  $I = [0, 1]$ . We say that  $\gamma_0$  and  $\gamma_1$  are  **$X$ -homotopic** if there is a continuous mapping  $H$  of the unit square  $I \times I$  into  $X$  such that

$$\begin{aligned} H(s, 0) &= \gamma_0(s), & H(s, 1) &= \gamma_1(s), & \text{for all } s &\in I \\ H(0, t) &= H(1, t), & & & \text{for all } t &\in I. \end{aligned} \quad (*)$$

- Put  $\gamma_t(s) = H(s, t)$ . Then  $(*)$  defines a one-parameter family of closed curves  $\gamma_t$  in  $X$ , which connects  $\gamma_0$  and  $\gamma_1$ . Intuitively, this means that  $\gamma_0$  can be continuously deformed to  $\gamma_1$ , within  $X$ .
- If  $\gamma_0$  is  $X$ -homotopic to a constant mapping  $\gamma_1$  (i.e., if  $\gamma_1^*$  consists of just one point), we say that  $\gamma_0$  is **null-homotopic** in  $X$ .

# Simply connected spaces

## Definition

If  $X$  is connected and if every closed curve in  $X$  is null-homotopic,  $X$  is said to be **simply connected**.

## Example

Every convex region  $\Omega$  is simply connected. To see this, let  $\gamma_0$  be a closed curve in  $\Omega$ , fix  $z_1 \in \Omega$ , and define

$$H(s, t) = (1 - t)\gamma_0(s) + tz_1 \quad \text{for all } s, t \in [0, 1].$$

## Lemma

Let  $\gamma_0, \gamma_1 : [0, 1] \rightarrow \mathbb{C}$  be closed paths. Let  $\alpha \in \mathbb{C}$ , if

$$|\gamma_1(s) - \gamma_0(s)| < |\alpha - \gamma_0(s)| \quad \text{for all } s \in I = [0, 1], \quad (\text{X})$$

then  $\text{Ind}_{\gamma_1}(\alpha) = \text{Ind}_{\gamma_0}(\alpha)$ .

# Homotopic curves

**Proof:** First we derive from (X) that  $\alpha \notin \gamma_0^*$  and  $\alpha \notin \gamma_1^*$ .

- If  $\alpha \in \gamma_0^*$ , then  $\alpha = \gamma_0(s)$  for some  $s \in I$  and then by (X), we obtain

$$0 \leq |\gamma_1(s) - \gamma_0(s)| < |\gamma_0(s) - \gamma_0(s)| < 0.$$

This is a contradiction.

- If  $\alpha \in \gamma_1^*$ , then  $\alpha = \gamma_1(s)$  for some  $s \in I$  and by (X), we obtain

$$|\gamma_1(s) - \gamma_0(s)| < |\gamma_1(s) - \gamma_0(s)|,$$

which is again a contradiction.

- Now, since  $\alpha \notin \gamma_0^*$ , and  $\alpha \notin \gamma_1^*$ , then

$$\text{Ind}_{\gamma_0}(\alpha) \quad \text{and} \quad \text{Ind}_{\gamma_1}(\alpha)$$

are defined.

# Homotopic curves

- We consider

$$\gamma(s) = \frac{\gamma_1(s) - \alpha}{\gamma_0(s) - \alpha} \quad \text{for } s \in I.$$

- We see that  $\gamma$  is a curve since  $\alpha \notin \gamma_0^*$ . Further,  $\gamma$  is a closed path since  $\gamma_0$  and  $\gamma_1$  are closed paths, and

$$\gamma'(s) = \frac{(\gamma_0(s) - \alpha) \gamma_1'(s) - (\gamma_1(s) - \alpha) \gamma_0'(s)}{(\gamma_0(s) - \alpha)^2}.$$

- We have

$$\gamma(s) - 1 = \frac{\gamma_1(s) - \alpha}{\gamma_0(s) - \alpha} - 1 = \frac{\gamma_1(s) - \gamma_0(s)}{\gamma_0(s) - \alpha}.$$

- Therefore by (X) we deduce

$$|\gamma(s) - 1| < 1 \quad \text{for } s \in I.$$

- Thus  $\gamma^* \subseteq D(1, 1)$ . Therefore 0 lies in the unbounded region determined by  $\gamma$  and hence  $\text{Ind}_\gamma(0) = 0$  by the index theorem.

# Homotopic curves

- Now

$$0 = \text{Ind}_\gamma(0) = \frac{1}{2\pi i} \int_\gamma \frac{dz}{z} = \frac{1}{2\pi i} \int_0^1 \frac{\gamma'(s)}{\gamma(s)} ds$$

- By the computations from the previous slide

$$\begin{aligned} \frac{\gamma'(s)}{\gamma(s)} &= \frac{(\gamma_0(s) - \alpha) \gamma_1'(s) - (\gamma_1(s) - \alpha) \gamma_0'(s)}{(\gamma_0(s) - \alpha)(\gamma_1(s) - \alpha)} \\ &= \frac{\gamma_1'(s)}{\gamma_1(s) - \alpha} - \frac{\gamma_0'(s)}{\gamma_0(s) - \alpha}. \end{aligned}$$

- Therefore

$$\frac{1}{2\pi i} \int_0^1 \frac{\gamma_1'(s)}{\gamma_1(s) - \alpha} ds = \frac{1}{2\pi i} \int_0^1 \frac{\gamma_0'(s)}{\gamma_0(s) - \alpha} ds,$$

and hence

$$\text{Ind}_{\gamma_0}(\alpha) = \text{Ind}_{\gamma_1}(\alpha). \quad \square$$



# Homotopic curves

## Theorem

If  $\Gamma_0$  and  $\Gamma_1$  are  $\Omega$ -homotopic closed paths in a region  $\Omega \subseteq \mathbb{C}$ , and if  $\alpha \notin \Omega$ , then

$$\text{Ind}_{\Gamma_1}(\alpha) = \text{Ind}_{\Gamma_0}(\alpha).$$

**Proof:** By definition, there is a continuous  $H : I^2 \rightarrow \Omega$  such that

$$\begin{aligned} H(s, 0) &= \Gamma_0(s), & H(s, 1) &= \Gamma_1(s), & \text{for all } s &\in I, \\ H(0, t) &= H(1, t) & \text{for all } t &\in I. \end{aligned}$$

- Since  $I^2$  is compact, so is  $H(I^2)$ . Moreover,  $\Omega^c$  is closed and  $\Omega \cap H(I^2) = \emptyset$ . Hence there exists  $\varepsilon > 0$  such that

$$|\alpha - H(s, t)| > 2\varepsilon \quad \text{if } (s, t) \in I^2.$$

# Homotopic curves

- Since  $H$  is uniformly continuous, there is  $n \in \mathbb{N}$  such that

$$|H(s, t) - H(s', t')| < \varepsilon \quad \text{if} \quad |s - s'| + |t - t'| \leq 1/n$$

- Define polygonal closed paths  $\gamma_0, \dots, \gamma_n$  by

$$\gamma_k(s) = H\left(\frac{i}{n}, \frac{k}{n}\right)(ns + 1 - i) + H\left(\frac{i-1}{n}, \frac{k}{n}\right)(i - ns)$$

if  $i - 1 \leq ns \leq i$  (equivalently  $0 \leq i - ns \leq 1$ ), and  $i = 1, \dots, n$ .

- Combining the last two inequalities, we obtain

$$\begin{aligned} |\gamma_k(s) - H(s, k/n)| &\leq |H(i/n, k/n) - H(s, k/n)|(ns + 1 - i) \\ &\quad + |H((i-1)/n, k/n) - H(s, k/n)|(i - ns) < \varepsilon \end{aligned}$$

for  $k = 0, \dots, n$  and  $s \in I$ .

# Homotopic curves

- In particular, taking  $k = 0$  and  $k = n$ , we obtain

$$|\gamma_0(s) - \Gamma_0(s)| < \varepsilon, \quad \text{and} \quad |\gamma_n(s) - \Gamma_1(s)| < \varepsilon.$$

- By the fact that  $|\alpha - H(s, t)| > 2\varepsilon$  for all  $(s, t) \in I^2$  and the last inequality from the previous slide  $|\gamma_k(s) - H(s, k/n)| < \varepsilon$  for  $s \in I$  and  $k = 0, \dots, n$ , we obtain that

$$|\alpha - \gamma_k(s)| > \varepsilon \quad \text{for} \quad k = 0, \dots, n \quad \text{and} \quad s \in I.$$

- Observe also that

$$\begin{aligned} |\gamma_{k-1}(s) - \gamma_k(s)| &\leq |H(i/n, (k-1)/n) - H(i/n, k/n)|(ns + 1 - i) \\ &\quad + |H((i-1)/n, (k-1)/n) - H((i-1)/n, k/n)|(i - ns) < \varepsilon \end{aligned}$$

for  $k = 0, \dots, n$  and  $s \in I$ .

- Hence

$$|\gamma_{k-1}(s) - \gamma_k(s)| < |\alpha - \gamma_k(s)|$$

for  $k = 0, \dots, n$  and  $s \in I$ .

# Homotopic curves

- Now by the previous lemma, observe that

$$\begin{aligned}
 |\gamma_n(s) - \Gamma_1(s)| < |\alpha - \gamma_n(s)| &\implies \text{Ind}_{\gamma_n}(\alpha) = \text{Ind}_{\Gamma_1}(\alpha), \\
 |\gamma_{n-1}(s) - \gamma_n(s)| < |\alpha - \gamma_n(s)| &\implies \text{Ind}_{\gamma_{n-1}}(\alpha) = \text{Ind}_{\gamma_n}(\alpha), \\
 &\vdots \\
 |\gamma_0(s) - \gamma_1(s)| < |\alpha - \gamma_1(s)| &\implies \text{Ind}_{\gamma_0}(\alpha) = \text{Ind}_{\gamma_1}(\alpha), \\
 |\gamma_0(s) - \Gamma_0(s)| < |\alpha - \gamma_0(s)| &\implies \text{Ind}_{\gamma_0}(\alpha) = \text{Ind}_{\Gamma_0}(\alpha).
 \end{aligned}$$

- This proves that

$$\text{Ind}_{\Gamma_1}(\alpha) = \text{Ind}_{\Gamma_0}(\alpha)$$

for every  $\alpha \in \Omega^c$  as desired. □

# Homotopic curves

## Theorem

*Suppose that  $\Omega \subseteq \mathbb{C}$  is a simply connected region. Then for every closed curve  $\Gamma$  in  $\Omega$  we have*

$$\text{Ind}_{\Gamma}(\alpha) = 0 \quad \text{whenever} \quad \alpha \notin \Omega.$$

**Proof:** The region  $\Omega$  is simply connected, hence every closed curve  $\Gamma$  in  $\Omega$  is null-homotopic. In other words, there exists a continuous  $H : I^2 \rightarrow \Omega$  such that

$$\begin{aligned} H(s, 0) &= \Gamma(s), & H(s, 1) &= \gamma(s), & \text{for all } s &\in I, \\ H(0, t) &= H(1, t) & \text{for all } t &\in I, \end{aligned}$$

where  $\gamma$  is a constant curve. Hence

$$\text{Ind}_{\gamma}(\alpha) = 0 \quad \text{whenever} \quad \alpha \notin \Omega.$$

By the previous theorem we obtain that  $\text{Ind}_{\Gamma}(\alpha) = \text{Ind}_{\gamma}(\alpha) = 0$  for  $\alpha \notin \Omega$  as desired. □

# Homotopic curves

## Remark

- The previous theorem shows that the global Cauchy theorem holds in simply connected regions  $\Omega \subseteq \mathbb{C}$ , since

$$\text{Ind}_{\Gamma}(\alpha) = 0, \quad \text{whenever } \alpha \notin \Omega$$

for every closed path  $\Gamma$  in  $\Omega$ .

- The last but one theorem shows that if  $\Gamma_0$  and  $\Gamma_1$  are  $\Omega$ -homotopic closed paths in a region  $\Omega \subseteq \mathbb{C}$ , and if  $\alpha \notin \Omega$ , then

$$\text{Ind}_{\Gamma_1}(\alpha) = \text{Ind}_{\Gamma_0}(\alpha),$$

which combined with the second part of the global Cauchy theorem ensures that

$$\int_{\Gamma_0} f(z) dz = \int_{\Gamma_1} f(z) dz.$$